

PIC16F716 Rev. A Silicon/Data Sheet Errata

The PIC16F716 parts you have received conform functionally to the Device Data Sheet (DS41206B) and the Programming Specification (DS40245B), except for the anomalies described below.

All problems listed here will be addressed in future revisions of the **PIC16F716 silicon**.

1. Module: Silicon (Rev. A4) – Programming

The oscillator circuitry may prevent proper initialization of the Programming mode when the part is programmed in-circuit.

Work around

Tie the OSC1/EXTCLK pin (pin 16 of 18-pin package or pin 18 of 20-pin package) to ground to disable the oscillator during In-circuit Serial Programming™.

Clarifications/Corrections to the Data Sheet:

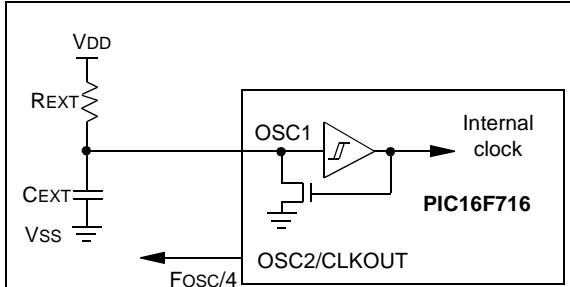
In the Device Data Sheet (DS41206B), the following clarifications and corrections should be noted.

1. Module: Oscillator Configuration

In Figure 9-3, revise the second line of recommended values as follows:

$$10 \text{ k}\Omega \leq R_{\text{EXT}} \leq 100 \text{ k}\Omega \quad (\text{VDD} < 3.0\text{V})$$

FIGURE 9-3: RC OSCILLATOR MODE



Recommended values:

- $3 \text{ k}\Omega \leq R_{\text{EXT}} \leq 100 \text{ k}\Omega \quad (\text{VDD} \geq 3.0\text{V})$
- $10 \text{ k}\Omega \leq R_{\text{EXT}} \leq 100 \text{ k}\Omega \quad (\text{VDD} < 3.0\text{V})$
- $C_{\text{EXT}} > 20 \text{ pF}$

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2. Module: Electrical Characteristics

In Section 12.4, "DC Characteristics: PIC16F716 (Industrial, Extended)", changes to parameter numbers D033A and D042B are shown in bold and italics below.

12.4 DC Characteristics: PIC16F716 (Industrial, Extended)

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +85^{\circ}\text{C}$ for industrial $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$ for extended Operating voltage VDD range as described in DC specification Section 12.1 "DC Characteristics: PIC16F716 (Industrial, Extended)" and Section 12.4 "DC Characteristics: PIC16F716 (Industrial, Extended)"				
Param No.	Sym	Characteristic	Min	Ty†	Max	Units	Conditions
D030 D030A D031 D032 D033 D033A	VIL	Input Low Voltage					
		I/O ports with TTL buffer	Vss	—	0.8V	V	$4.5\text{V} \leq \text{VDD} \leq 5.5\text{V}$ otherwise (Note 1)
		with Schmitt Trigger buffer	Vss	—	0.15VDD	V	
		MCLR, OSC1 (in RC mode)	Vss	—	0.2VDD	V	
		OSC1 (in HS mode)	Vss	—	0.2VDD	V	
		OSC1 (in XT and LP modes)	Vss	—	0.3VDD	V	
D040 D040A D041 D042 D042A D042B D043	VIH	Input High Voltage					
		I/O ports with TTL buffer	2.0	—	VDD	V	$4.5\text{V} \leq \text{VDD} \leq 5.5\text{V}$ otherwise For entire VDD range (Note 1)
		with Schmitt Trigger buffer	0.25 VDD + 0.8V	—	VDD	V	
		MCLR	0.8 VDD	—	VDD	V	
		OSC1 (HS)	0.7 VDD	—	VDD	V	
		OSC1 (XT and LP modes)	1.6	—	VDD	V	
D060 D061 D063	IIL	Input Leakage Current^{(2), (3)}					
		I/O ports	—	—	± 1	μA	$\text{Vss} \leq \text{VPIN} \leq \text{VDD}$, Pin at high-impedance $\text{Vss} \leq \text{VPIN} \leq \text{VDD}$ $\text{Vss} \leq \text{VPIN} \leq \text{VDD}$, XT, HS and LP Oscillator modes
		MCLR, RA4/T0CKI	—	—	± 5	μA	
		OSC1/CLKIN	—	—	± 5	μA	
D070	IPURB	PORTB weak pull-up current	TBD	250	TBD	μA	$\text{VDD} = 5\text{V}$, $\text{VPIN} = \text{VSS}$
D080 D083	VOL	Output Low Voltage					
		I/O ports	—	—	0.6	V	$\text{IOL} = 8.5\text{ mA}$, $\text{VDD} = 4.5\text{V}$, $-40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}$ $\text{IOL} = 7.0\text{ mA}$, $\text{VDD} = 4.5\text{V}$, $-40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}$ $\text{IOL} = 1.6\text{ mA}$, $\text{VDD} = 4.5\text{V}$, $-40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}$ $\text{IOL} = 1.2\text{ mA}$, $\text{VDD} = 4.5\text{V}$, $-40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}$
		OSC2/CLKOUT (RC Oscillator mode)	—	—	0.6	V	
			—	—	0.6	V	
D090 D092	VOH	Output High Voltage					
		I/O ports⁽³⁾	VDD – 0.7	—	—	V	$\text{IOH} = -3.0\text{ mA}$, $\text{VDD} = 4.5\text{V}$, $-40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}$ $\text{IOH} = -2.5\text{ mA}$, $\text{VDD} = 4.5\text{V}$, $-40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}$ $\text{IOH} = -1.3\text{ mA}$, $\text{VDD} = 4.5\text{V}$, $-40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}$ $\text{IOH} = -1.0\text{ mA}$, $\text{VDD} = 4.5\text{V}$, $-40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}$
		OSC2/CLKOUT (RC Oscillator mode)	VDD – 0.7	—	—	V	
			VDD – 0.7	—	—	V	
D150*	VOD	Open-Drain High Voltage	—	—	8.5	V	RA4 pin
D100 D101	COSC2 Cl0	Capacitive Loading Specs on Output Pins					
		OSC2/CLKOUT pin	—	—	15	pF	In XT, HS and LP modes when external clock is used to drive OSC1.
		All I/O pins and OSC2 (in RC mode)	—	—	50	pF	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note 1:** In RC Oscillator mode, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended that the PIC® microcontroller be driven with external clock in RC mode.
- 2:** The leakage current on the MCLR/VPP pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.
- 3:** Negative current is defined as current sourced by the pin.

3. Module: Interrupts

The IOCB register is not used on this device. The interrupt-on-change feature will automatically be enabled for any RB<7:4> configured as an input.

See **Section 3.2 “PORTB and the TRISB Register”** in the data sheet (DS41206B) for more information.

REGISTER 2-3: INTCON: INTERRUPT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-x
GIE	PEIE	TOIE	INTE	RBIE	T0IF ⁽¹⁾	INTF	RBIF
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as ‘0’

-n = Value at POR

‘1’ = Bit is set

‘0’ = Bit is cleared

x = Bit is unknown

bit 7	GIE: Global Interrupt Enable bit 1 = Enables all unmasked interrupts 0 = Disables all interrupts
bit 6	PEIE: Peripheral Interrupt Enable bit 1 = Enables all unmasked peripheral interrupts 0 = Disables all peripheral interrupts
bit 5	TOIE: Timer0 Overflow Interrupt Enable bit 1 = Enables the Timer0 interrupt 0 = Disables the Timer0 interrupt
bit 4	INTE: RB0/INT External Interrupt Enable bit 1 = Enables the RB0/INT external interrupt 0 = Disables the RB0/INT external interrupt
bit 3	RBIE: PORTB Change Interrupt Enable bit 1 = Enables the PORTB change interrupt 0 = Disables the PORTB change interrupt
bit 2	T0IF: Timer0 Overflow Interrupt Flag bit ⁽¹⁾ 1 = TMRO register has overflowed (must be cleared in software) 0 = TMRO register did not overflow
bit 1	INTF: RB0/INT External Interrupt Flag bit 1 = The RB0/INT external interrupt occurred (must be cleared in software) 0 = The RB0/INT external interrupt did not occur
bit 0	RBIF: PORTB Change Interrupt Flag bit 1 = When at least one of the PORTB general purpose I/O pins changed state (must be cleared in software) 0 = None of the PORTB general purpose I/O pins have changed state

Note 1: T0IF bit is set when Timer0 rolls over. Timer0 is unchanged on Reset and should be initialized before clearing T0IF bit.

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4. Module: ADC

Corrected values for the acquisition time example for the 8-bit ADC used by this device are shown below.

EQUATION 7-1: ACQUISITION TIME EXAMPLE

Assumptions: Temperature = 50°C and external impedance of 10kΩ 5.0V VDD

$$\begin{aligned}TACQ &= \text{Amplifier Settling Time} + \text{Hold Capacitor Charging Time} + \text{Temperature Coefficient} \\&= TAMP + TC + TCOFF \\&= 5\mu s + TC + [(Temperature - 25^\circ C)(0.05\mu s/\text{ }^\circ C)]\end{aligned}$$

The value for TC can be approximated with the following equations:

$$\begin{aligned}V_{APPLIED}\left(1 - \frac{1}{511}\right) &= V_{CHOLD} && ;[1] V_{CHOLD} \text{ charged to within 1/2 lsb} \\V_{APPLIED}\left(1 - e^{-\frac{TC}{RC}}\right) &= V_{CHOLD} && ;[2] V_{CHOLD} \text{ charge response to } V_{APPLIED} \\V_{APPLIED}\left(1 - e^{-\frac{TC}{RC}}\right) &= V_{APPLIED}\left(1 - \frac{1}{511}\right) && ;\text{combining [1] and [2]}\end{aligned}$$

Solving for TC:

$$\begin{aligned}TC &= -C_{HOLD}(R_{IC} + R_{SS} + R_S) \ln(1/511) \\&= -10pF(1k\Omega + 7k\Omega + 10k\Omega) \ln(0.0019569) \\&= 1.12\mu s\end{aligned}$$

Therefore:

$$\begin{aligned}TACQ &= 5\mu s + 1.12\mu s + [(50^\circ C - 25^\circ C)(0.05\mu s/\text{ }^\circ C)] \\&= 7.37\mu s\end{aligned}$$

APPENDIX A: REVISION HISTORY

Rev. A Document (2/19/04)

First revision of this document.

Rev. B Document (7/12/04)

Changes made to parameter numbers D033A and D042B in Section 12.4, "DC Characteristics: PIC16F716 (Industrial, Extended)".

Rev. C Document (3/28/07)

Changes made to the data sheet revision referenced (DS41206B), emphasis added in Figure 9-3, "RC Oscillator Mode", to the second recommended value, removed note 1 in register 2-3, "INTCON: Interrupt Control Register", and adjusted values in Equation 7-1 "Acquisition Time Example".

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